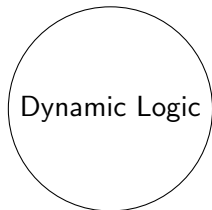


# Dynamic Logic

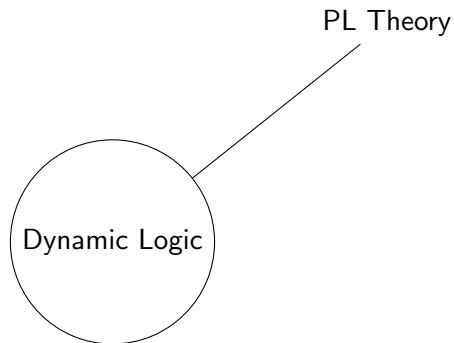
How loops are actually recursion  
Hype for Types

Jacob Neumann

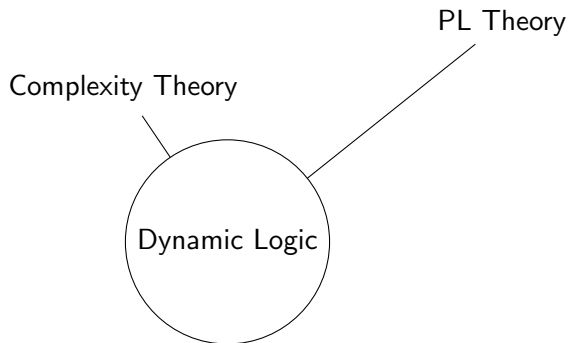
05 March 2019



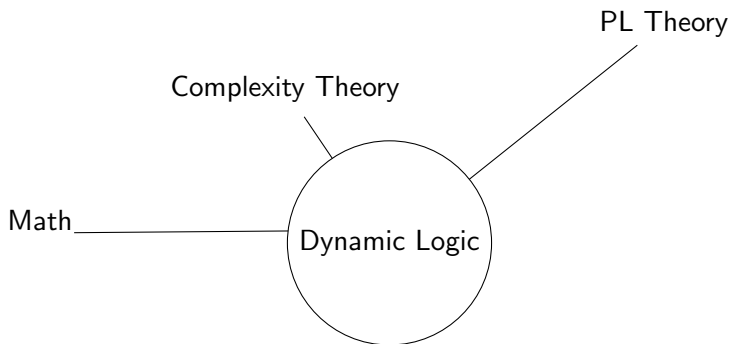
# Dynamic Logic is everywhere



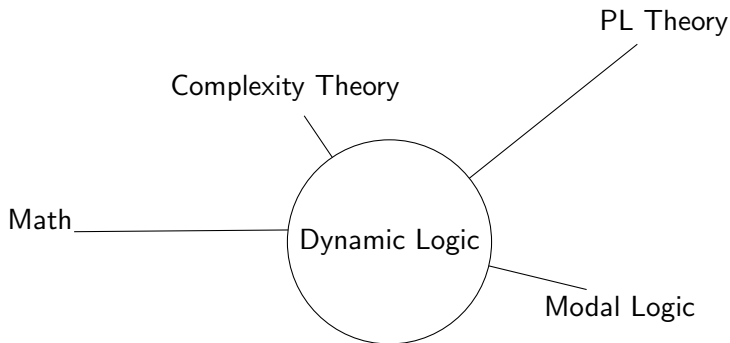
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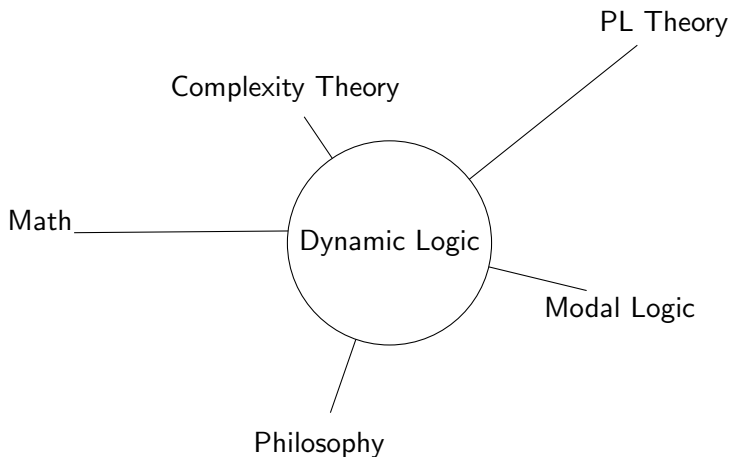
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# Table of Contents

- 1 Syntax and Semantics
- 2 Deterministic PDL
- 3 Proving Behavior in DPDL
- 4 Hoare Logic
- 5 Other Cool Stuff







**IMPERATIVE CODE AHEAD**



**IMPERATIVE CODE AHEAD**  
**(also math)**

# Section 1

## Syntax and Semantics

# Some philosophy...

Question: What is programming?

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(One possible) answer:

- Programming is the art of communicating with computers

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(One possible) answer:

- Programming is the art of communicating with computers
- We communicate with computers using otherwise-meaningless strings of symbols

# Some philosophy...



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while true: print("AHHHH")
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fun fact 0 = 1
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# Operational vs. Denotational

There are two main approaches to specifying programming language semantics: **operational semantics** and **denotational semantics**.

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In this lecture, I'll be focusing on the *denotational* approach.

## Section 2

# Deterministic PDL



Deterministic Propositional Dynamic Logic (DPDL) is a formal semantics for interpreting a basic programming language.

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- A state space
- Interpretations of all the programs as *partial functions* on the state space
- A apparatus for formulating logical statements about the state space

# The State Space

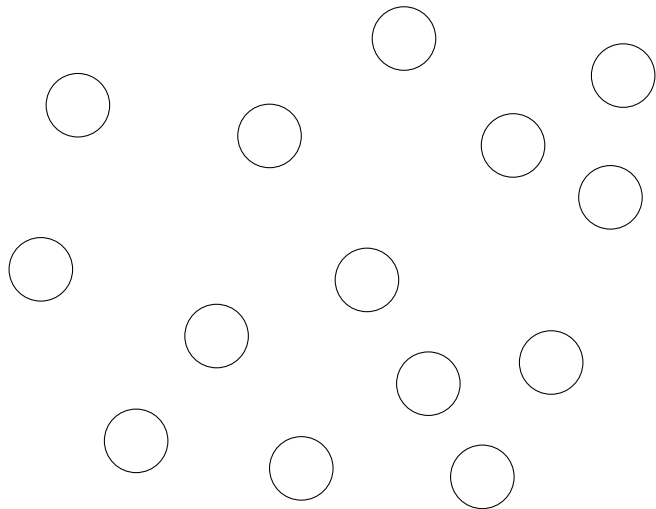
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# The State Space

We mathematically model a computer as a *set  $X$  of internal states (or configurations)*. The behavior of our programs will depend on the state of the computer.

$X$  is often either finite or countably infinite, although in some applications we will want to have more states.

# The State Space



# The Programs

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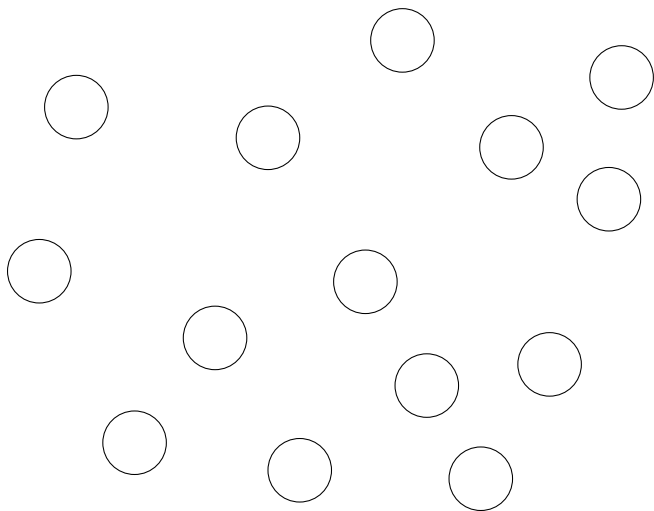
Each program symbol  $\pi \in \Pi$  *denotes* a partial function on our state space.

We write this as:

$$\|\pi\| : X \rightarrow X$$

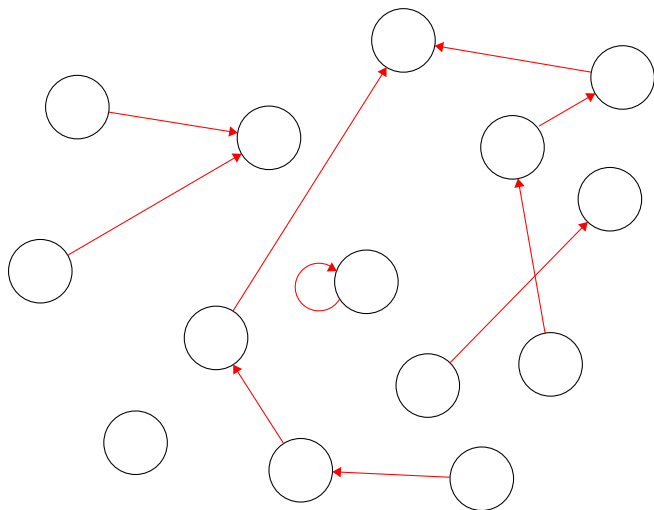
So, for each state  $x \in X$ , “executing  $\pi$  at  $x$ ” will either succeed (terminate) and result in a new state  $\|\pi\|(x)$ , or it will crash (encoded by  $\|\pi\|(x)$  being undefined).

# The Programs



# The Programs

$\pi_0$





# The Propositions

Let  $\Phi = \{p_0, p_1, \dots\}$  be a countable set of “propositional variables”. These propositional variables denote logical statements we might want to make about a state  $x$ .

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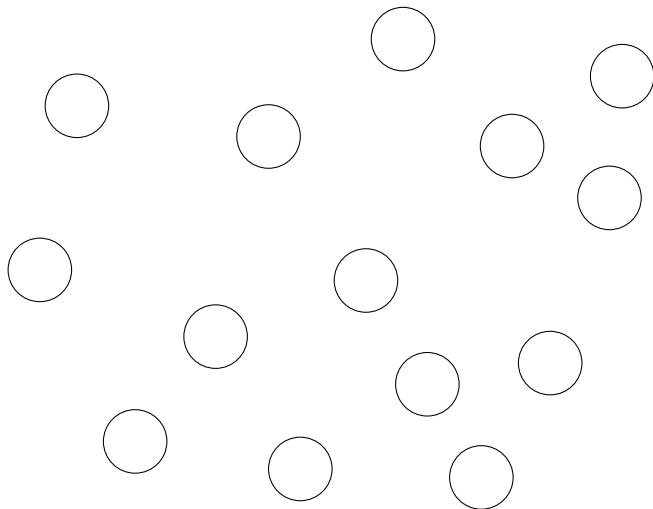
Let  $\Phi = \{p_0, p_1, \dots\}$  be a countable set of “propositional variables”. These propositional variables denote logical statements we might want to make about a state  $x$ .

Each propositional variable  $p \in \Phi$  denotes a subset of our state space. We write this as:

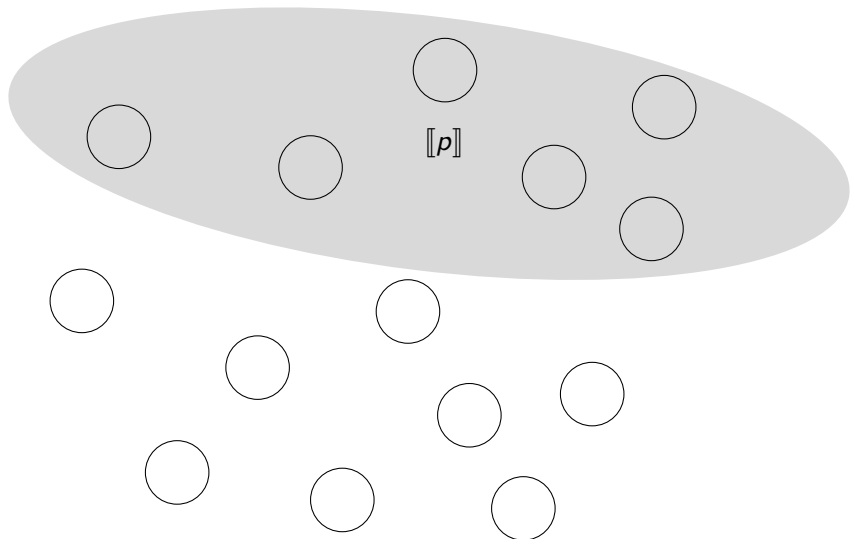
$$\llbracket p \rrbracket \subseteq X$$

Think of  $\llbracket p \rrbracket$  as the set of states where  $p$  is true.

# The Propositions

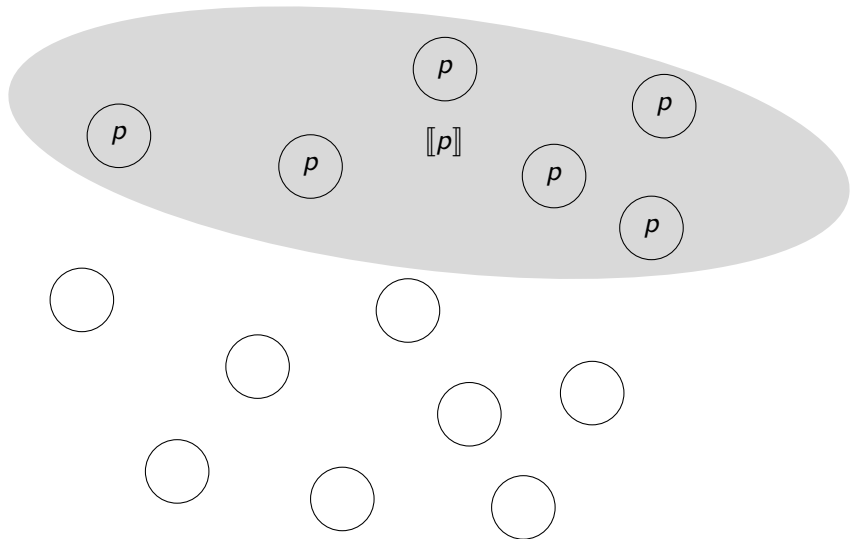


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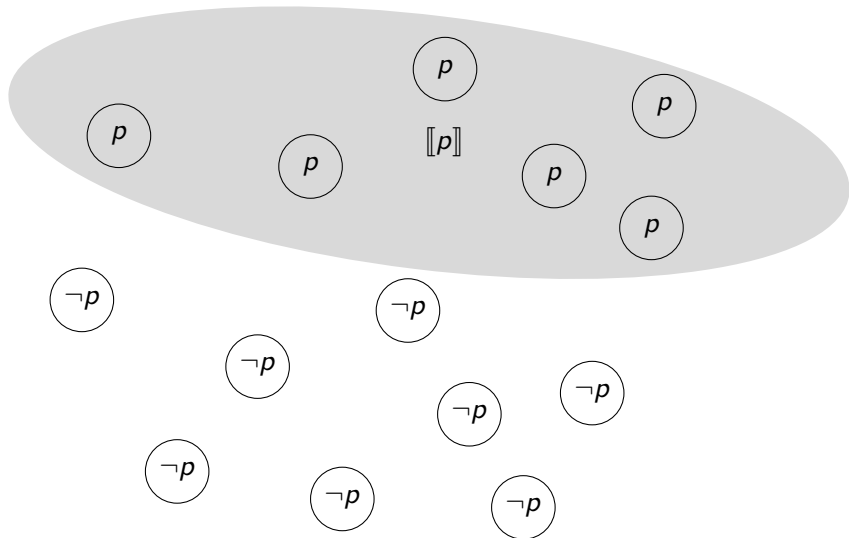




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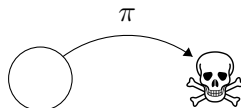
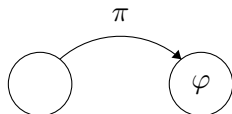
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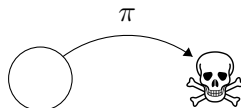
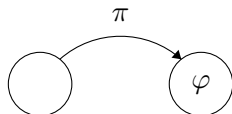
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The formula  $\langle \pi \rangle \varphi$ , which is defined to be  $\neg[\pi]\neg\varphi$ , expresses the statement “ $\pi$  terminates, and results in a  $\varphi$  state”.

# Sanity Check: What does this formula say?

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- Sequencing, conditionals, and loops
- A logical syntax to talk about state properties before and after executing a function

## Section 3

# Proving Behavior in DPDL

Based on how we set up the logic, the following rules are true **at every state of every model**, for any programs  $\pi, \pi_1, \pi_2$  and any formulas  $\varphi, \psi, \theta$ :

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- $$\frac{(\varphi \wedge \psi) \rightarrow [\pi]\psi}{\psi \rightarrow [\mathbf{while} \ \varphi \ \mathbf{do} \ \pi](\neg\varphi \wedge \psi)}$$

# Section 4

## Hoare Logic



# From PDL to Hoare Logic

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- $\{n \geq 0\} i := n \{i \geq 0\}$
- $\{a = b^i\} a := a * b \{a = b^{i+1}\}$

Here are our rules from earlier, in the Hoare notation:



$$\frac{\{\varphi\} \pi_1 \{\psi\} \quad \{\psi\} \pi_2 \{\theta\}}{\{\varphi\} \pi_1; \pi_2 \{\theta\}}$$



$$\frac{\{\varphi\} \pi_1 \{\psi\} \quad \{\neg\varphi\} \pi_2 \{\psi\}}{\{\} \mathbf{if} \varphi \mathbf{then} \pi_1 \mathbf{else} \pi_2 \{\psi\}}$$



$$\frac{\{\varphi \wedge \psi\} \pi \{\psi\}}{\{\psi\} \mathbf{while} \varphi \mathbf{do} \pi \{\neg\varphi \wedge \psi\}}$$

# A 122-style example

```
i:=n;  
res:=1;  
(while (i>0)  
do  
  
    res := res * b;  
    i := i-1  
  
);
```

# A 122-style example

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- Heap Allocation
- Concurrency
- Recursion and Fixed-Point Operators
- Functional Programming
- Cost Semantics
- Hoare Calculus + Types!
- More complex mathematics to make the modal logic more powerful (topological structure, structure-preserving maps and category theory, etc.)

Thank you!